Infrared Data Communications Presentation Part 1 November 13,2021 (J. Briante)

Topics

Electromagnetic Spectrum, Devises IrDA Infrared communication Infrared Emitting Diode

- Angle of half intensity: ϕ ,
- Relative radian power vs wave length

Infrared Receiver

- Series for remote control
 - Automatic gain control (AGC), Data format compatibility

Data Encoding Methods

• Pulse distance encoding, Pulse width encoding, Manchester bi-phase encoding

Basic IR System –IR emitter/receiver

- External components/software
- Generating Pulses
 - With PSoC PWM interrupts, Raspberry Pi Pico State Machine
- Receiving Pulse
 - Raspberry Pi Pico using interrupts
 - Single Pulse Application Example

IR Receiver for Continues Data Communication

• What works for RS-232 data transmission and why

Project Utilising IR emitters/Receivers using RS-232 Communication

Reference

Electromagnetic spectrum









Infrared Data Association (IrDA) Developed in 1993

- wireless data transfer over short rage using point-and-shoot principles
- implemented in portable devices such as mobile telephones, laptops, cameras, printers, and medical devices
- Range :
 - standard: 2 m
 - low-power to low-power: 0.2 m
 - standard to low-power: 0.3 m
- Angle: minimum cone ±15°
- Speed: 2.4 kbit/s to 1 Gbit/s

IrDA Infrared communication Module Rohm Semiconductor RPM871

- Designed for low power consumption at waiting mode (Typ.73μA)
- Suitable for sets driven by battery due to power down control function
- Power supply voltage range : 2.6V to 3.6V 5)
- Constant LED load resistance can change transmission distance. (Approx. 20 to 60cm)



Infrared Emitting Diode With $\lambda p = 940$ nm

- Vishay, TSAL6100 tsal6100.pdf (vishay.com)
 - Angle of half intensity: $\phi = \pm 10^{\circ}$
 - Peak wavelength: $\lambda p = 940 \text{ nm}$
- Vishay, VSLY5940 vsly5940.pdf (vishay.com)
 - Angle of half intensity: $\phi = \pm 3^{\circ}$
 - Peak wavelength: $\lambda p = 940 \text{ nm}$
- Other Manufacturers With $\lambda p = 940$ nm
 - Broadcom, LITEON, Everlight, Lamex, ...





Fig. 9 - Relative Radiant Intensity vs. Angular Displacement

Fig. 8 - Relative Radiant Power vs. Wavelength



λ - Wavelength (m

Fig. 8 - Relative Radiant Intensity vs. Angular Displacement

Fig. 7 - Relative Radiant Power vs. Wavelength

Vishay's **Series** for Remote Control 3-Pin Devices



Vishay's **Series** for Remote Control

- Basically there are six categories of IR receive based on:
 - Data format (encoding/decoding methods used by various manufacturers)
 - Sonny, RCA, NEC, Panasonic, Sharp, etc.
 - Noise suppression (reduced by AGC) due to environmental factors
 - fluorescent lamps, dimmed LCD panels, emit noise in the infrared spectrum
 - Surface Mounted (8)
 - Through Hole (5)
- Range: ≈20 m
- Frequency: from 30 kHz to 57 kHz

Other Manufacturers:

COMPATIBILITY OF THE TSOP RECEIVER MODULES WITH DATA FORMATS

Vishay offers a variety of IR receiver series in order to supply an optimised solution for each application. Guidelines for selecting the best part for each data format is given here.

Basically there are six categories of IR receiver settings regarding noise suppression and data format compatibility. The summary of the features of these AGC types is listed here:

- AGC1 is compatible with any coding scheme, it is optimized for continuous data transmission
- AGC2 is optimized for most common remote control standard applications with typical long burst data formats
- AGC3 is optimized for short burst data formats in noisy environments

- AGC4 is optimized for most common remote control standard applications in very noisy environments (including dimmed LCD backlightings)
- AGC5 is optimized for short burst data formats in very noisy environments
- AGC6 has best sensitivity for NEC and RC5 code in Cyllene series receivers and offers high robustness against smart phone interference in Mneme series receivers
- AGC-S and AGC-C are optimized for Sony code and Cisco code respectively. These AGCs are exclusively designed for Aether series receivers

The tables below provide an overview of which IR receiver

CYLLENE IC (TSOP9) - COMPATIBILITY FOR DATA FORMATS							
	AGC1	AGC2	AGC3	AGC4	AGC5	AGC6	BEST CHOICE
NEC	yes	yes	yes	yes	yes	yes	AGC6
RC5 code	yes	yes	yes	yes	yes	yes	AGC6
RC6 mode 0	yes	yes	yes	yes	yes	yes	AGC4
RCMM	yes	no	yes	no	yes	no	AGC3
RECS-80 code	yes	no	yes	no	yes	no	AGC3
R-2000 code (33 kHz)	yes	yes	yes	yes	yes	yes	AGC6
Mitsubishi code 38 kHz	yes	yes	yes	yes	yes	yes	AGC6
Sony code SIRCS 12 bit	yes	yes	no	no	no	yes	AGC2
Sony code SIRCS 15 bit	yes	yes	no	no	no	yes	AGC2
Sony code SIRCS 20 bit	yes	yes	no	no	no	no	AGC2
r-map data format 38 kHz	yes	no	yes	no	yes	no	AGC5
r-step data format 38 kHz	yes	no	yes	no	yes	no	AGC3
r-step data format for KB 56 kHz	yes	no	yes	yes	yes	yes	AGC4
XMP code	yes	no	yes	no	yes	no	AGC3
Cisco format 57kHz	yes	yes	no	no	no	yes	AGC2
Cisco format 37kHz	yes	yes	no	yes	yes	yes	AGC6
Low latency protocol - worst case frame 16 bit	yes	yes	yes	yes	yes	yes	AGC6
Low latency protocol - extended frame 24 bit	yes	yes	no	yes	yes	yes	AGC6
Sejin 4PPM format (38 kHz or 56 kHz)	yes	no	yes	yes	yes	no	AGC4
MCIR code keyboard package timing	yes	no	yes	no	yes	no	AGC3
MCIR code pointing device timing	yes	no	yes	no	yes	no	AGC3
MCIR code remote control timing	yes	no	yes	no	yes	no	AGC3
Konka TV data format 2004	yes	yes	yes	yes	yes	yes	AGC6
RCA code 56 kHz	yes	yes	no	yes	yes	yes	AGC4
Panasonic 36.7 kHz	yes	yes	yes	yes	yes	yes	AGC6
Sharp 38 kHz	yes	no	yes	yes	yes	yes	AGC6

MNEME IC (TSOP1) - COMPATIBILITY FOR DATA FORMATS							
	AGC1	AGC2	AGC3	AGC4	AGC5	AGC6	BEST CHOICE
NEC	yes	yes	yes	yes	yes	yes	AGC4
RC5 code	yes	yes	yes	yes	yes	yes	AGC6
RC6 mode 0	yes	yes	yes	yes	yes	no	AGC4
RCMM	yes	no	yes	no	yes	no	AGC3
RECS-80 code	yes	no	yes	no	yes	no	AGC3
R-2000 code (33 kHz)	yes	yes	yes	yes	yes	yes	AGC4
Mitsubishi code 38 kHz	yes	yes	yes	yes	yes	no	AGC4
Sony code SIRCS 12 bit	yes	yes	yes	no	no	yes	AGC2
Sony code SIRCS 15 bit	yes	yes	yes	no	no	yes	AGC2
Sony code SIRCS 20 bit	yes	yes	no	no	no	no	AGC2
r-map data format 38 kHz	yes	no	yes	no	yes	no	AGC3
r-step data format 38 kHz	yes	yes	yes	yes	yes	no	AGC4
r-step data format for KB 56 kHz	yes	yes	yes	yes	yes	no	AGC4
XMP code	yes	no	yes	no	yes	no	AGC3
Cisco format 57kHz	yes	yes	no	no	no	yes	AGC2
Cisco format 37kHz	yes	yes	yes	yes	yes	yes	AGC6
Low latency protocol - worst case frame 16 bit	yes	yes	yes	yes	yes	yes	AGC6
Low latency protocol - extended frame 24 bit	yes	yes	yes	yes	yes	yes	AGC6
Sejin 4PPM format (38 kHz or 56 kHz)	yes	yes	yes	yes	yes	no	AGC4
MCIR code keyboard package timing	yes	yes	yes	yes	yes	no	AGC4
MCIR code pointing device timing	yes	yes	yes	yes	yes	no	AGC4
MCIR code remote control timing	yes	yes	yes	yes	yes	no	AGC4
Konka TV data format 2004	yes	yes	yes	yes	yes	yes	AGC4
RCA code 56 kHz	yes	yes	yes	yes	no	yes	AGC6
Panasonic 36.7 kHz	yes	no	yes	yes	yes	no	AGC4
Sharp 38 kHz	yes	no	yes	yes	yes	no	AGC4

Data Encoding Methods



Pulse Distance Encoding

Figure 2 shows how the distances between bursts of pulses are used to encode (and decode) 0's and 1's. A 0 is encoded with a longer distance between bursts than a 1 in the example shown.



Pulse Width Encoding

Figure 3 shows how the envelope of the pulse bursts (otherwise known as the pulse width) is used to encode data. A 0 is encoded with a wider pulse width than a 1 in the example shown.



Manchester Biphase Encoding

Figure 4 illustrates manchester biphase encoding. In this example, a 1 is encoded such that the first half of a bit period has pulses and the second half has none. A 0 is encoded such that the first half of a bit period has no pulses and the second half has pulses.





Basic IR System





Transmitter End External Components:

- Microcontroller
 - 8-bit \$1.00 micro will do
- Resistor to a GPIO pin to
 - Limit current <20ma
- IR emitter to match λ of IR receiver
 - Like tsal1600
- Software
 - Generate n pulses
 - at frequency of IR receiver

Receiver End External Components:

- Microcontroller or Not
 - Logic gates
 - Do some think
- IR receiver
 - Most type will do
 - No continuous data
- Software
 - Poll pin or generate interrupt
 - Do some think

Generating Pulses Using a PWM and a tsop 4156 56 Kz IR Receiver



Example Calculations Using a Clock of 24 MHz (any other clock frequency can be used)

- Using a 56 KZ IR receiver
- 24 MHz / 56 Kz ≈ 429
 - Set the period of the PWM to 428
 - Set the compare value to $428/2 \approx 214$ for 50% duty cycle

Test Program Using Interrupts



```
void Gen_Pulses(void)
{
    if(PulseCount!=0)
    PWM_Start();
    while(PulseCount !=0) {}
    PWM_WritePeriod(428);
    PWM_Stop();
}
```





Generating Pulses Using Raspberry Pi Pico State machine

Finite-State Machines

- A computing system (mathematical mode) that can be in only one of n-states
- Transition from one state to another other state is determined by input to current state
- All around us computer science theory, digital circuits, everyday algorithms, etc.



Generating Pulses Using Raspberry Pi Pico State machine

Finite-State Machines in Microcontrollers (FSM)

- All arm bases microcontroller may incorporate FSM
 - Including Raspberry Pi Pico
- Cypress PSoC Microcontrollers
 - All Digital Blocks (UDB) are State Machine (reduces libraries)
 - Digital logic –gates, flip flops, registers, mux, de-mux
 - Digital Function counter, shift register, pwm, quadrature encoders, plus more
 - Digital Communication Blocks

Raspberry Pi Pico State Machine



```
1 # Raspberry Pi Pico outputting n pulses to IR emitter using PIO (State Machine)
 2 import time
 3 from time import sleep
 4 from machine import Pin
  import rp2
 5
 6
   @rp2.asm_pio(set_init=rp2.PIO.OUT_LOW)
   def nPulse_56kz():
 7
       pull()
 8
       mov(x, osr) # num pulses
 9
     label ("start")
10
   set(pins, 1) [30] #31 cycles
11
   set(pins, 0) [30] #31 cycles
12
       jmp(x_dec, "start") #2 cycles
13
14
                                  # calculating frequence: f = 64 \times 56000=3564000 \text{ hz}
15 # Create the StateMachine 8 pulse @ 57kz, outputting on Pin(25).
16 sm = rp2.StateMachine(0, nPulse 56kz, freq=3584000, set base=Pin(15),out base=Pin(15))
17 # Start the StateMachine.
18 while True:
19
       sm.put(5)
20
   sm.active(1)
      time.sleep_ms(1)
21
       sm.active(0)
22
23
```

Generating n Pulses Raspberry Pi Pico State Machine







Pico Flashing LED on IR Pulse Received



```
from machine import Pin
   import utime
  led = Pin(25, Pin.OUT)
   IR_Receiver = Pin(15, Pin.IN, Pin.PULL_UP)
   global Loop Count
5
   Loop Count = 20
   global Flag
   Flag = False
8
   led.value(⊘)
9
   def IR_Receiver_callback(pin):
       global Flag
       Flag = True
12
   IR_Receiver.irq(IR_Receiver_callback, Pin.IRQ_FALLING)
   while(True):
14
       if Flag:
15
           i = Loop_Count
16
           while i >0:
               led.toggle()
18
               utime.sleep_ms(50)
19
20
               i= i-1
21
           Flag = False
```



Application of Single Burst IR Pulses Force Landing a Quadcopter Following an IR Hit





The throttle signal from RC receiver

- is connected to the micro and passed on flight controller of the quadcopter
- If an IR hit is sensed by the micro
 - operator loses throttle control only
 - micro slowly reduces throttle signal forcing the quadcopter to land
 - Following a time out throttle control restores

Force Landing a Quadcopter Following an IR Hit





Vishay's TSDP Receiver Series for Infrared RS232 Communication

TSDP Series:

- TSDP series devices differ from standard infrared receivers for remote control
- frequencies are tuned to the needs of RS-232 communication
- pulse-width accuracy has been improved
- 1200 bps to 9600 bps over a range of up to 35 meters
- either 38.4 kHz or 57.6 kHz

TSDP34138 IR Receiver:

- Frequency : 38.4 kHz
- Data Rate: 4800 bps

TSDP devices may be used for RS-232 Data Communications (AGC1 low-noise/ AGC3 typical-noise environment)

DATA RATE (bps)	CARRIER FREQUENCY (kHz)	CYCLES PER MARK / SPACE	AGC1 LOW-NOISE ENVIRONMENTS	AGC3 TYPICAL-NOISE ENVIRONMENTS
9600	57.6	6	TSDP34156, TSDP37156, TSDP36156	TSDP34356, TSDP37356, TSDP36356
4800	57.6	12	TSDP34156, TSDP37156, TSDP36156	
4800	38.4	8	TSDP34138, TSDP37138, TSDP36138	TSDP34338, TSDP37338, TSDP36338
2400	38.4	16	TSDP34138, TSDP37138, TSDP36138	

TSDP34138 special case : 4800 bps, 38.4 kHz, and AGC1

- any possible data pattern can be received indefinitely
- In all other combinations in the table, data patterns exist that will trigger the AGC
 - data patterns exist that data transmission may need to be interrupted periodically to allow the AGC to recover



tB : burst length

Dt : envelope duty cycle

Dt = tB/TB : burst time divided by the burst repetition time

Two Worst-Case Data Patterns

alternating 1-0-1-0: Dt =0.5







Burst length [N cycles of carrier]



Burst length [N cycles of carrier]

Generating Mark/Space Pulses in RS-232 Data Stream (AGC1 typical-noise environment)

Solutions

- Cypress PSoC Devices
 - Simple solution
- Raspberry Pi Pico
 - State Machine ?
 - External Nand Gates
 - Other

Solution Using PSoC 4 Microcontroller



Example Calculations Using a Clock of 24 MHz (any other clock frequency can be used)

- Using a 38.4KZ IR receiver
- 24 MHz / 38.4 KZ ≈ 625
 - Set the period of the PWM to 624
 - Set the compare value to $624/2 \approx 312$ for 50% duty cycle



Tx Byte : 10101010 = 0xAA= 170





Tektronix TDS 2012 TWO CHANNEL OSCILLOSCOPE

100 MHz 1 GS/s

MENL

CHI Acq Complete M Pas Coupling **BW Limit** 20MHz Volts/Div Coarse Probe 102 E Invert Off CH1 \ 1.28V CH1 2.00VBy CH2 2.00VBy M 50.0 us <10Hz

References <u>Finite-state machine - Wikipedia</u>

Vishay Data Formats for IR Remote Control

• <u>untitled (vishay.com)</u>

TSDP34138: RS232 Communication

- tsdp341.pdf (vishay.com)
- Tsop4156 IR Receiver(s)
 - <u>tsop45.pdf (vishay.com)</u>

ROHM: IrDA Infrared communication Module RPM871

<u>RPM871 : IrDA Infrared Communication Modules (digikey.com)</u>

IR Emitters

- Vishay TSAL6100 tsal6100.pdf (vishay.com)
 - Angle of half intensity: $\phi = \pm 10^{\circ}$
 - Peak wavelength: $\lambda p = 940 \text{ nm}$
- Vishay VSLY5940 vsly5940.pdf (vishay.com)
 - Angle of half intensity: $\phi = \pm 3^{\circ}$
 - Peak wavelength: λp = 940 nm

End Part1